## DESCRIPTION

The A3085A is a half-duplex RS-485 transceiver with $\pm 15 \mathrm{kV}$ IEC 61000-4-2 contact ESD protection. This device contains one driver and one receiver. The A3085A includes fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be logic high even if all transmitters on a terminated bus are disabled. The A3085A features reduced slew-rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps. The A3085A has a $1 / 8$ unit load receiver input impedance that allows up to 256 transceivers on the bus.

The A3085A is available in SOP8 package

ORDERING INFORMATION

| Package Type | Part Number |  |  |
| :---: | :--- | :--- | :---: |
| SOP8 | M8 | A3085AM8R |  |
| SPQ: 2,500pcs/Reel |  | A3085AM8VR |  |
| Note |  | V: Halogen free Package <br> R: Tape \& Reel |  |

AiT provides all RoHS products

## FEATURES

- $\quad+3.3 \mathrm{~V}$ or +5 V Operation
- True Fail-Safe Receiver
- Maximum Data Rate: $500 \mathrm{kbps}\left(\mathrm{V}_{\mathrm{cc}}=5 \mathrm{~V}\right)$

$$
250 \mathrm{kbps}(\mathrm{Vcc}=3.3 \mathrm{~V})
$$

- Allow Up to 256 Transceivers on the Bus
- I/O Pins ESD Protection: $\pm 15 \mathrm{kV}$ IEC 61000-4-2, Contact Discharge
- Available in SOP8 package


## APPLICATION

- Smart Meter
- DVR
- RS-485 Communications
- Level Translators
- Transceivers for EMI-Sensitive Applications
- Industrial-Control Local Area Networks
- Energy Meter Networks
- Lighting Systems


## TYPICAL APPLICATION



Typical Half-Duplex RS-485 Network

## PIN DESCRIPTION

|  |  |  |
| :---: | :---: | :---: |
| Pin \# | Symbol | Functions |
| 1 | RO | Receiver Output. |
| 2 | /RE | Receiver Output Enable. /RE is low to enable the Receiver; /RE is high to disable the Receiver. |
| 3 | DE | Driver Output Enable. DE is high to enable the Driver; DE is low to disable the Driver. |
| 4 | DI | Driver Input |
| 5 | GND | Ground. |
| 6 | A | Non-inverting Receiver Input and Non-inverting Driver Output. |
| 7 | B | Inverting Receiver Input and Inverting Driver Output. |
| 8 | Vcc | Power Supply. |

## FUNCTION TABLE

| Transmitting |  |  |  |  | Receiving |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inputs |  |  | Outputs |  | Inputs |  |  | Outputs |
| /RE | DE | DI | A | B | /RE | DE | A-B | RO |
| X | 1 | 1 | 1 | 0 | 0 | X | $>-50 \mathrm{mV}$ | 1 |
| X | 1 | 0 | 0 | 1 | 0 | X | <-200mV | 0 |
|  |  | 0 | 0 |  | 0 | X | Open/Shorted | 1 |
| 0 | 0 | X | High-Z | High-Z | 1 | 1 | X | High-Z |
| 1 | 0 | X |  |  | 1 | 0 | X | Shutdown <br> ( High-Z ) |

## ABSOLUTE MAXIMUM RATINGS

| Vcc, Power Supply | +7 V |
| :--- | ---: |
| $/ R E, D E$, Control Input Voltage | $-0.3 \mathrm{~V} \sim \mathrm{Vcc}+0.3 \mathrm{~V}$ |
| DI, Transmitter Input Voltage | $-0.3 \mathrm{~V} \sim \mathrm{Vcc}+0.3 \mathrm{~V}$ |
| A, B, Transmitter Output Voltage | $\pm 13 \mathrm{~V}$ |
| A, B, Receiver Input Voltage | $\pm 13 \mathrm{~V}$ |
| RO, Receiver Output Voltage | $-0.3 \mathrm{~V} \sim \mathrm{Vcc}^{+}+0.3 \mathrm{~V}$ |
| Operating Temperature | $-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$ |
| Storage Temperature | $-65^{\circ} \mathrm{C} \sim+150^{\circ} \mathrm{C}$ |
| Operating Junction Temperature | $125^{\circ} \mathrm{C}$ |

Stress beyond above listed "Absolute Maximum Ratings" may lead permanent damage to the device. These are stress ratings only and operations of the device at these or any other conditions beyond those indicated in the operational sections of the specifications are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

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## DC ELECTRICAL CHARACTERISTICS

(5V Operation)
$\mathrm{V}_{\mathrm{Cc}}=+5 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$, Typical Values are $\mathrm{V}_{\mathrm{cc}}=+5 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ NOTE1

| Parameter | Symbol | Conditions |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply | Vcc |  |  | 4.5 | - | 5.5 | V |
| Driver |  |  |  |  |  |  |  |
| Differential Driver Output (no load) | Vod1 | Figure 1 |  | - | - | Vcc | V |
| Differential Driver Output | Vod2 | Figure 1, R=27 $\Omega$ |  | 1.5 | - | - | V |
| Change in Magnitude of Differential Output Voltage ${ }^{\text {NOTE2 }}$ | $\Delta \mathrm{V}_{\text {OD }}$ | Figure 1, $\mathrm{R}=27 \Omega$ |  | - | - | 0.2 | V |
| Driver Common-mode Output Voltage | Voc | Figure 1, R=27 $\Omega$ |  | 1.0 | - | 3.0 | V |
| Change in Magnitude of Common-Mode Voltage ${ }^{\text {NOTE2 }}$ | $\Delta \mathrm{Voc}$ | Figure 1, R=27 $\Omega$ |  | - | - | 0.2 | V |
| Input High Voltage | $\mathrm{V}_{\text {IH }}$ | DE, DI, /RE |  | 2.0 | - | - | V |
| Input Low Voltage | $\mathrm{V}_{\text {IL }}$ | DE, DI, /RE |  | - | - | 0.8 | V |
| DI Input Hysteresis | VHYS |  |  | - | 100 | - | mV |
| Input Current(A and B) | lin4 | DE=GND, $\mathrm{V}_{\mathrm{cc}}=$ GND or 5.25 V | $\mathrm{V}_{\text {IN }}=12 \mathrm{~V}$ | - | - | 125 | $\mu \mathrm{A}$ |
|  |  |  | $\mathrm{V}_{\text {IN }}=-7 \mathrm{~V}$ | -75 | - | - |  |
| Driver Short-Circuit Output Current | losd | A Pin Short to B Pin |  | -100 | - | 100 | mA |
| Receiver |  |  |  |  |  |  |  |
| Receiver Differential Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Cm}} \leq 12 \mathrm{~V}$ |  | -200 | -125 | -50 | mV |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ |  |  | - | 40 | - | mV |
| Receiver Output High Voltage | V OH | $\mathrm{I}_{0}=-8 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-50 \mathrm{mV}$ |  | 4.0 | - | - | V |
| Receiver Output Low Voltage | Vol | $\mathrm{IO}=8 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-200 \mathrm{mV}$ |  | - | - | 0.4 | V |
| Three-State Output Current at Receiver | lozr |  |  | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| Receiver Input Resistance | $\mathrm{R}_{\text {IN }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {См }} \leq 12 \mathrm{~V}$ |  | 96 | - | - | $\mathrm{k} \Omega$ |
| Receiver Output Short-Circuit Current | losR | $0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Ro}} \leq \mathrm{V}_{\mathrm{Cc}}$ |  | $\pm 7$ | - | $\pm 95$ | mA |
| Supply Current |  |  |  |  |  |  |  |
| Supply Current | Icc | No load, /RE= DI=GND or $\mathrm{V}_{\mathrm{cc}}$ | $\mathrm{DE}=\mathrm{V}_{\mathrm{cc}}$ | - | 350 | 600 | $\mu \mathrm{A}$ |
|  |  |  | DE=GND | - | 370 | 600 | $\mu \mathrm{A}$ |
| Supply Current in Shutdown Mode | Ishdn | $\begin{aligned} & \mathrm{DE}=\mathrm{GND}, / \mathrm{RE}=\mathrm{V} \\ & \mathrm{DI}=\mathrm{V}_{\mathrm{cc}} \text { or } \mathrm{GND} \end{aligned}$ |  | - | - | 10 | $\mu \mathrm{A}$ |

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## (3.3V Operation)

$\mathrm{V}_{\mathrm{C}}=+3.3 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$, Typical Values are $\mathrm{V} \mathrm{CC}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}^{\text {NOTE }} 1$

| Parameter | Symbol | Conditions |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply | Vcc |  |  | 3 | - | 3.6 | V |
| Driver |  |  |  |  |  |  |  |
| Differential Driver Output (no load) | Vod1 | Figure 1 |  | - | - | Vcc | V |
| Differential Driver Output | Vod2 | Figure 1, $\mathrm{R}=27 \Omega$ |  | 0.8 | 1.15 | - | V |
| Change in Magnitude of Differential Output Voltage ${ }^{\text {NOTE }} 2$ | $\Delta \mathrm{V}_{\text {OD }}$ | Figure 1, $\mathrm{R}=27 \Omega$ |  | - | - | 0.2 | V |
| Driver Common-mode Output Voltage | Voc | Figure 1, $\mathrm{R}=27 \Omega$ |  | 1.0 | - | 3.0 | V |
| Change in Magnitude of Common-Mode Voltage ${ }^{\text {NOTE } 2}$ | $\Delta \mathrm{Voc}$ | Figure 1, $\mathrm{R}=27 \Omega$ |  | - | - | 0.2 | V |
| Input High Voltage | $\mathrm{V}_{\text {IH }}$ | DE,DI,/RE |  | 2.0 | - | - | V |
| Input Low Voltage | $V_{\text {IL }}$ | DE,DI,/RE |  | - | - | 0.8 | V |
| DI Input Hysteresis | $\mathrm{V}_{\mathrm{HYS}}$ |  |  | - | 100 | - | mV |
| Input Current(A and B ) | lina | DE=GND, $\mathrm{V}_{\mathrm{cc}}=$ GND or 3.6 V | $\mathrm{V}_{\text {IN }}=12 \mathrm{~V}$ | - | - | 125 | $\mu \mathrm{A}$ |
|  |  |  | $\mathrm{V}_{\text {IN }}=-7 \mathrm{~V}$ | -75- | - | - |  |
| Driver Short-Circuit Output Current | losd | A Pin Short to B Pin |  | -100 | - | 100 | mA |
| Receiver |  |  |  |  |  |  |  |
| Receiver Differential Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leqq \mathrm{~V}_{\text {См }} \leqq 12 \mathrm{~V}$ |  | -200 | -125 | -50 | mV |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ |  |  | - | 40 | - | mV |
| Receiver Output High Voltage | V OH | $\mathrm{IO}=-1.5 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-50 \mathrm{mV}$ |  | 4.0 | - | - | V |
| Receiver Output Low Voltage | Vol | $\mathrm{IO}_{\mathrm{O}}=2.5 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-200 \mathrm{mV}$ |  | - | - | 0.4 | V |
| Three-State Output Current at Receiver | lozr |  |  | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| Receiver Input Resistance | $\mathrm{R}_{\mathrm{IN}}$ | $-7 \mathrm{~V} \leqq \mathrm{~V}_{\text {См }} \leqq 12 \mathrm{~V}$ |  | 96 | - | - | $\mathrm{k} \Omega$ |
| Receiver Output Short-Circuit Current | losr | $0 \mathrm{~V} \leqq \mathrm{~V}_{\mathrm{Ro}} \leqq \mathrm{V}_{\mathrm{cc}}$ |  | $\pm 7$ | - | $\pm 95$ | mA |
| Supply Current |  |  |  |  |  |  |  |
| Supply Current | Icc | No load, /RE= $\mathrm{DI}=\mathrm{GND}$ or $\mathrm{V}_{\mathrm{cc}}$ | $\mathrm{DE}=\mathrm{V}$ cc | - | 270 | 600 | $\mu \mathrm{A}$ |
|  |  |  | DE=GND | - | 290 | 600 | $\mu \mathrm{A}$ |
| Supply Current in Shutdown Mode | Ishon | $\begin{aligned} & \mathrm{DE}=\mathrm{GND}, / \mathrm{RE}=\mathrm{V}_{\mathrm{cc}}, \\ & \mathrm{DI}=\mathrm{V}_{\mathrm{cc}} \text { or } \mathrm{GND} \end{aligned}$ |  | - | - | 10 | $\mu \mathrm{A}$ |

NOTE1: All currents into the device are positive. All currents out of the device are negative. All voltages are referred to device ground unless otherwise noted
NOTE2: $\Delta V_{O D}$ and $\Delta V_{O C}$ are the changes in $V_{O D}$ and $V_{o c}$, respectively, when the DI input changes state.

## SWITCHING CHARACTERISTICS

(5V Operation)
$\mathrm{V}_{\mathrm{cc}}=+5 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$, Typical values @ $\mathrm{V} \mathrm{Cc}=+5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Input to Output | tDPLH | Figure 3 and $5, \mathrm{R}_{\text {dIFF }}=54 \Omega$ | - | 300 | 800 | ns |
|  | tDPHL | $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | - | 300 | 800 |  |
| Driver Output Skew <br> \|TDPLH - TDPHL | toskew | Figure 3 and 5 , $R_{\text {DIFF }}=54 \Omega$ $C_{L 1}=C_{L 2}=100 \mathrm{pF}$ | - | - | 100 | ns |
| Driver Rise or Fall Time | $t_{\text {DR }}, t_{\text {dF }}$ | Figure 3 and $5, R_{\text {dIFF }}=54 \Omega$ $C_{L 1}=C_{L 2}=100 \mathrm{pF}$ | - | 420 | 900 | ns |
| Maximum Data Rate | $\mathrm{F}_{\text {MAX }}$ |  | 500 | - | - | kbps |
| Driver Enable to Output High | $t_{\text {DzH }}$ | Figure 4 and 6, CL=100pF S2 Closed | - | - | 300 | ns |
| Driver Enable to Output Low | tozl | Figure 4 and 6, $C_{L}=100 \mathrm{pF}$ S1 Closed | - | - | 500 | ns |
| Driver Disable Time from Low | tolz | Figure 4 and 6, $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$ S1 Closed | - | - | 900 | ns |
| Driver Disable Time from High | $t_{\text {DHz }}$ | Figure 4 and 6, CL=15pF S2 Closed | - | - | 800 | ns |
| Receiver Input to Output | $t_{\text {RPLH }}$ $t_{\text {RPHL }}$ | Figure 7 and $9,\left\|V_{I D}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leqq 15 \mathrm{~ns}$ | - | 150 | 300 | ns |
| \|TRPLH - $\mathrm{T}_{\text {RPHL }} \mid$ Differential Receiver Skew | $t_{\text {RSKD }}$ | Figure 7 and $9,\left\|\mathrm{~V}_{\mathrm{ID}}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leqq 15 \mathrm{~ns}$ | - | 10 | - | ns |
| Receiver Enable to Output Low | $t_{\text {RzL }}$ | Figure 2 and 8 , <br> $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S 1 Closed | - | 20 | 50 | ns |
| Receiver Enable to Output High | $t_{\text {RzH }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF} \text { S2 Closed }$ | - | 20 | 50 | ns |
| Receiver Disable Time from Low | $t_{\text {RLZ }}$ | Figure 2 and 8 , $C_{R L}=15 \mathrm{pF}$ S 1 Closed | - | 30 | 60 | ns |
| Receiver Disable Time from High | $t_{\text {RHZ }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF} \text { S2 Closed }$ | - | 30 | 60 | ns |
| Time to Shutdown | tshdn |  | - | 500 | 1000 | ns |
| Driver Enable from Shutdown to Output High | tozH(SHDN) | Figure 4 and6 , CL=100pF S2 Closed | - | - | 2500 | ns |
| Driver Enable from Shutdown to Output Low | tozl(SHDN) | Figure 4 and 6 , CL=100pF S1 Closed | - | - | 2500 | ns |
| Receiver Enable from Shutdown to Output High | trzH(SHDN) | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF} \text { S2 Closed }$ | - | - | 2500 | ns |
| Receiver Enable from Shutdown to Output Low | $\mathrm{t}_{\text {RZL }}$ (SHDN) | Figure 2 and 8 , CRL=15pF S1 Closed | - | - | 2500 | ns |

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## (3.3V Operation)

$\mathrm{V}_{\mathrm{cc}}=+3.3 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$, Typical values are at $\mathrm{V} \mathrm{Cc}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Input to Output | t ${ }_{\text {DPLH }}$ | Figure 3 and $5, R_{\text {DIFF }}=54 \Omega$ $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | - | 280 | 800 | ns |
|  | $t_{\text {DPHL }}$ |  | - | 280 | 800 |  |
| Driver Output Skew <br> \|TDPLH $-T_{\text {DPHL }} \mid$ | toskew | Figure 3 and $5, R_{\text {diFF }}=54 \Omega$ $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | - | - | 100 | ns |
| Driver Rise or Fall Time | tDR, tbF | Figure 3 and $5, R_{\text {DIFF }}=54 \Omega$ $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | - | 450 | 900 | ns |
| Maximum Data Rate | $\mathrm{F}_{\text {max }}$ |  | 250 | - | - | kbps |
| Driver Enable to Output High | $t_{\text {DzH }}$ | Figure 4 and 6, CL=100pF S2 Closed | - | - | 300 | ns |
| Driver Enable to Output Low | tozl | Figure 4 and 6, CL=100pF S1 Closed | - | - | 500 | ns |
| Driver Disable Time from Low | tolz | Figure 4 and 6, CL=15pF S1 Closed | - | - | 900 | ns |
| Driver Disable Time from High | $t_{\text {DHZ }}$ | Figure 4 and 6, $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$ S2 Closed | - | - | 800 | ns |
| Receiver Input to Output | $\begin{aligned} & \mathrm{t}_{\mathrm{RPLH}} \\ & \mathrm{t}_{\mathrm{RPHL}} \end{aligned}$ | Figure 7 and $9,\left\|V_{I D}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leqq 15 \mathrm{~ns}$ | - | 150 | 300 | ns |
| \|TRPLH - $\mathrm{T}_{\text {RPHL }}$ \| Differential Receiver Skew | $t_{\text {RSKD }}$ | Figure 7 and $9,\left\|V_{\text {ID }}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leqq 15 \mathrm{~ns}$ | - | 10 | - | ns |
| Receiver Enable to Output Low | $t_{\text {RzL }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S1 Closed | - | 20 | 50 | ns |
| Receiver Enable to Output High | $t_{\text {RzH }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S2 Closed | - | 20 | 50 | ns |
| Receiver Disable Time from Low | $t_{\text {RLZ }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S1 Closed | - | 30 | 60 | ns |
| Receiver Disable Time from High | trhz | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S2 Closed | - | 30 | 60 | ns |
| Time to Shutdown | tshDN |  | - | 500 | 1000 | ns |
| Driver Enable from <br> Shutdown to Output High | tozH(SHDN) | Figure 4 and6 , CL=100pF S2 Closed | - | - | 2500 | ns |
| Driver Enable from <br> Shutdown to Output Low | tozl(SHDN) | Figure 4 and 6 , $C_{L}=100 \mathrm{pF}$ S1 Closed | - | - | 2500 | ns |
| Receiver Enable from Shutdown to Output High | trzH(SHDN) | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S2 Closed | - | - | 2500 | ns |
| Receiver Enable from Shutdown to Output Low | $t_{\text {RZL(SHDN) }}$ | Figure 2 and 8 , $\mathrm{C}_{\mathrm{RL}}=15 \mathrm{pF}$ S1 Closed | - | - | 2500 | ns |

## TEST CIRCUITS AND TIMING DIAGRAMS

Figure 1 : Driver DC Test Load


Figure 3 : Driver Timing Test Circuit


Figure 5 : Driver Propagation Delays


Figure 2 : Receiver Enable/Disable Timing Test Load


Figure 4 : Driver Enable/Disable Timing test Load


Figure 6 : Driver Enable and Disable Times


Figure 7 : Receiver Propagation Delays


Figure 8 : Receiver Enable and Disable Times


Figure 9 : Receiver Propagation Delay Test Circuit


## BLOCK DIAGRAM



## PACKAGE INFORMATION

## Dimension in SOP8 (Unit: mm)



| Symbol | Min | Max |
| :---: | :---: | :---: |
| A | - | 1.77 |
| A1 | 0.08 | 0.28 |
| A2 | 1.20 | 1.60 |
| A3 | 0.55 | 0.75 |
| b | 0.39 | 0.48 |
| b1 | 0.38 | 0.44 |
| c | 0.20 | 0.26 |
| c1 | 0.19 | 0.21 |
| D | 4.70 | 5.10 |
| E | 5.80 | 6.20 |
| E1 | 3.70 | 4.10 |
| e | 1.27 BSC |  |
| h | 0.25 | 0.50 |
| L | 0.50 | 0.80 |
| L1 | 1.05 REF |  |
| $\theta$ | $0^{\circ}$ | $8^{\circ}$ |

## IMPORTANT NOTICE

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